

Bayesian sequential testing and estimation in discrete time

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Outline

- 1 Introduction**
 - Statistics & Optimal stopping
 - Motivation for us
- 2 Sequential composite hypothesis testing**
 - Set-up
 - Structural properties
- 3 Sequential estimation**
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 - Structural properties
- 4 Applications in control: an example**

Statistics & Optimal stopping

Classical problem: Testing the unknown drift of a BM.

- Observe the trajectory of a BM with unknown drift:

$$X_t = \Theta t + W_t.$$

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- The time to stop observing is part of the decision.

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- Standard method: explicit solution: [Shiryaev \(1969\)](#).

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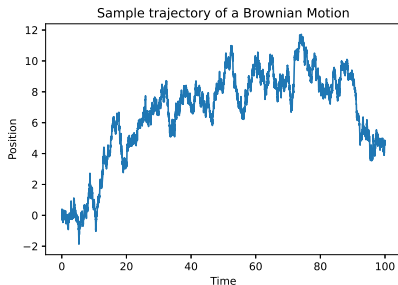
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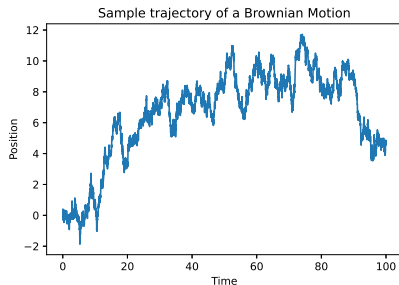


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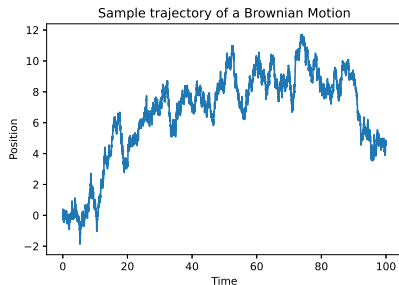
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This motivates us to consider things in **discrete time**.

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- Explicit solutions?
- Otherwise, what structural properties does the problem exhibit?

What are we building on?

Discrete time: popular in the 60s and 70s

- Studied on a case-by-case basis and rely on conjugate priors: Lindley and Barnett (1965), Moriguti and Robbins (1962).
- Focus on asymptotic behaviour: Schwartz (1962), Bickel (1973), Lai (1988).
- c.f. Sobel (1953), Alvo (1977), Cablio (1977).

Continuous time: many generalisations

- Finite horizon: Gapeev and Peskir (2004), Poisson: Peskir and Shiryaev (2000), multi-dimensional: Ekström and Wang (2022).
- Most literature uses binary priors (c.f. Zhitlukhin and Shiryaev (2011), Ekström and Vaicenavicius (2015), Ekström, Karatzas & Vaicenavicius (2022)).

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- μ : (arbitrary) prior of the unknown parameter Θ
- Denote the support of μ by S , and $S^+ := S \cap \theta_0, \infty$.

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- Define the posterior probability process Π

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Can we do Markovian embedding?

Properties of the Π process

- At time n , given $X_1 = x_1, \dots, X_n = x_n$, by the Bayes theorem,

$$\begin{aligned} & \mathbb{P}(\Theta > \theta_0 | X_1 = x_1, \dots, X_n = x_n) \\ &= \frac{\int_{S^+} \prod_{i=1}^n p_u(x_i) \mu(du)}{\int_S \prod_{i=1}^n p_u(x_i) \mu(du)} \\ &= \frac{\int_{S^+} \exp\{u \sum_{i=1}^n x_i - nB(u)\} \mu(du)}{\int_S \exp\{u \sum_{i=1}^n x_i - nB(u)\} \mu(du)}. \end{aligned}$$

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- Denoting $Y_n := \sum_{i=1}^n X_i$:

$$\Pi_n = q(n, Y_n).$$

where

$$q(n, y) := \frac{\int_{S^+} e^{uy - nB(u)} \mu(du)}{\int_S e^{uy - nB(u)} \mu(du)}.$$

Parameterize the posterior distribution

Denote by

$$\mu_{n,y}(du) := \frac{e^{uy-nB(u)}\mu(du)}{\int_{\mathcal{S}} e^{uy-nB(u)}\mu(du)}$$

the posterior distribution of Θ at time n conditional on $Y_n = y$.

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Main result 1: concavity

Define $\mathbb{P}_{n,\pi}(\cdot) := \mathbb{P}(\cdot | \Pi_n = \pi)$. The optimal stopping problem can be written as

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Lemma (Dynamic programming)

The value function $V(n, \pi)$ satisfies

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Lemma (Preservation of concavity)

Let $f : [0, 1] \rightarrow [0, \infty)$ be a concave function. Then $\pi \mapsto \mathbb{E}_{n,\pi}[f(\Pi_{n+1})]$ is concave on $(0, 1)$.

Main result 1: concavity

Theorem (Concavity)

The function $\pi \mapsto V(n, \pi)$ is concave for each fixed $n \geq 0$.

Introduce now

- The continuation region \mathcal{C} :

$$\mathcal{C} := \{(n, \pi) \in \mathbb{N}_0 \times [0, 1] : V(n, \pi) < \pi \wedge (1 - \pi)\},$$

- The stopping region \mathcal{D} by

$$\mathcal{D} := \{(n, \pi) \in \mathbb{N}_0 \times [0, 1] : V(n, \pi) = \pi \wedge (1 - \pi)\}.$$

- The stopping time

$$\tau^* := \inf\{k \geq 0 : (n + k, \Pi_{n+k}) \in \mathcal{D}\}$$

is an optimal strategy.

Main result 1: concavity

The continuation region is of the form $(b_1(n), b_2(n))$

Main result 2: concentration of the posterior

The posterior distribution squeezes in

If $a < \theta_0 < b$, then

$$n \mapsto \mathbb{P}_{n,\pi}(\Theta \leq a) \quad \& \quad n \mapsto \mathbb{P}_{n,\pi}(\Theta > b)$$

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As a consequence, the π -level curves are spreading out.

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An assumption

For any $\pi \in (0, 1)$ and $n \geq m \geq 0$, the random variable $\Pi_{m+1}|\{\Pi_m = \pi\}$ dominates $\Pi_{n+1}|\{\Pi_n = \pi\}$ in convex order.

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- No counter-example is found.

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For any $\pi \in (0, 1)$ and $n \geq m \geq 0$, the random variable $\Pi_{m+1}|\{\Pi_m = \pi\}$ dominates $\Pi_{n+1}|\{\Pi_n = \pi\}$ in convex order.

- Assume the above holds. Then $V(n, \pi)$ is non-decreasing in n , and the boundaries are monotone.
- But does this assumption always hold? **A:** We don't know.

Time-monotonicity?

- Holds for some examples with **any** prior (Gaussian w. unknown mean, Bernoulli, Binomial).
- Holds for some other examples for **some families** of priors (Exp, Gaussian w. unknown variance).
- No counter-example is found.

Conjecture: V is non-decreasing in n .

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 - Statistics & Optimal stopping
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- 2 **Sequential composite hypothesis testing**
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Introduction

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What is the value of the unknown parameter?

- Want to obtain an accurate estimate in the presence of cost.
- We can ask similar questions as in the testing problem. (remind the audience the questions)

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The coordinate

Define the *posterior estimate process*:

$$\hat{\Theta}_n := \mathbb{E} \left[\Theta | \mathcal{F}_n^X \right].$$

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Want to minimize:

$$\mathbb{E} \left[(\Theta - \hat{\Theta}_\tau)^2 + c\tau \right]$$

over stopping times.

Markovian embedding

Similarly, we are fine in this coordinate because

$\hat{\Theta}_n = G_n(Y_n)$ is a strictly increasing bijection.

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- Define $\Psi(n, \hat{\Theta}_n) = \text{Var}(\Theta | \mathcal{F}_n^X)$, then V can be written in the θ_0 coordinate:

$$V(n, \theta_0) = \inf_{\tau \in \mathcal{T}} \mathbb{E}_{n, \theta_0} [\Psi(n + \tau, \hat{\Theta}_{n+\tau}) + c\tau].$$

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- Note that $M_n := \Psi(n, \hat{\Theta}_n) + \hat{\Theta}_n^2$ is a martingale, we can further write

$$\begin{aligned} V(n, \theta_0) &= \Psi(n, \theta_0) + \inf_{\tau \in \mathcal{T}} \mathbb{E}_{n, \theta_0} \left[\sum_{i=0}^{\tau} \left(c - \left(\hat{\Theta}_{i+1}^2 - \hat{\Theta}_i^2 \right) \right) \right] \\ &=: \Psi(n, \theta_0) + v(n, \theta_0). \end{aligned}$$

Main result: conditions for space-monotonicity

First-order stochastic dominance

If $\theta_0 \leq \tilde{\theta}_0$, then $\mathbb{P}(\hat{\Theta}_n^{\theta_0} \leq a) \geq \mathbb{P}(\hat{\Theta}_n^{\tilde{\theta}_0} \leq a)$, for all $a \in \mathbb{R}$ and all $n \geq 0$.

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Space-monotonicity of v

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This implies a **one-sided** stopping boundary.

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- What about time-monotonicity? We have some partial results. e.g.
...

The structure of continuation/stopping

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$$V = \sup_{\{p_n\}_{n \geq 0}} \mathbb{E} \left[\sum_{n=0}^{\infty} e^{-rn} p_n D(p_n) \right].$$

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Economic & operations research literatures: incomplete learning, myopic strategy c.f. [McLennan 1984](#), [Harrison 2012](#).

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- The value can be written as

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This leads to some problems of "exploration-exploitation" type.

Summary

To summarise the talk:

- We study the Bayesian sequential **testing** and **estimation** problems in discrete time.
- The unknown parameter is taken from the **exponential family**.
- The prior can be arbitrary.
- In general, no explicit solutions. We are after structural properties.
- The problems we study open up doors to certain control problems.

Thank you for your attention!

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