

Lecture 12. American Options.

Last time. Basic optimal stopping theory \Rightarrow free bdr problems.

Today. Examples.

Example 12.1 (Perpetual American put option).

We wish to find the optimal exercising time of an American put with strike $K > 0$, and with the underlying described in the risk-neutral setting by.

$$dX_t = \underbrace{(r - \delta)} X_t dt + \sigma dB_t.$$

where $r > 0$ is the risk-free rate, $\delta \in [0, r)$ is the dividend.

We can exercise it at anytime $t \geq 0$, it never expires.

$$\text{payoff at } t : (K - X_t)^+.$$

Step 1. Write down the value function, C, D and T^* .

$$V(x) = \sup_{\tau} \mathbb{E}_x \left[\underbrace{e^{-r\tau}}_{\text{risk-neutral pricing}} (K - X_\tau)^+ \right].$$

\rightarrow dividend is hidden here

"fair price".

• What does the continuation region C look like?

"When it's good enough, stop"

when $x \geq k$, should always wait! $\Rightarrow [k, \infty) \subset C$.

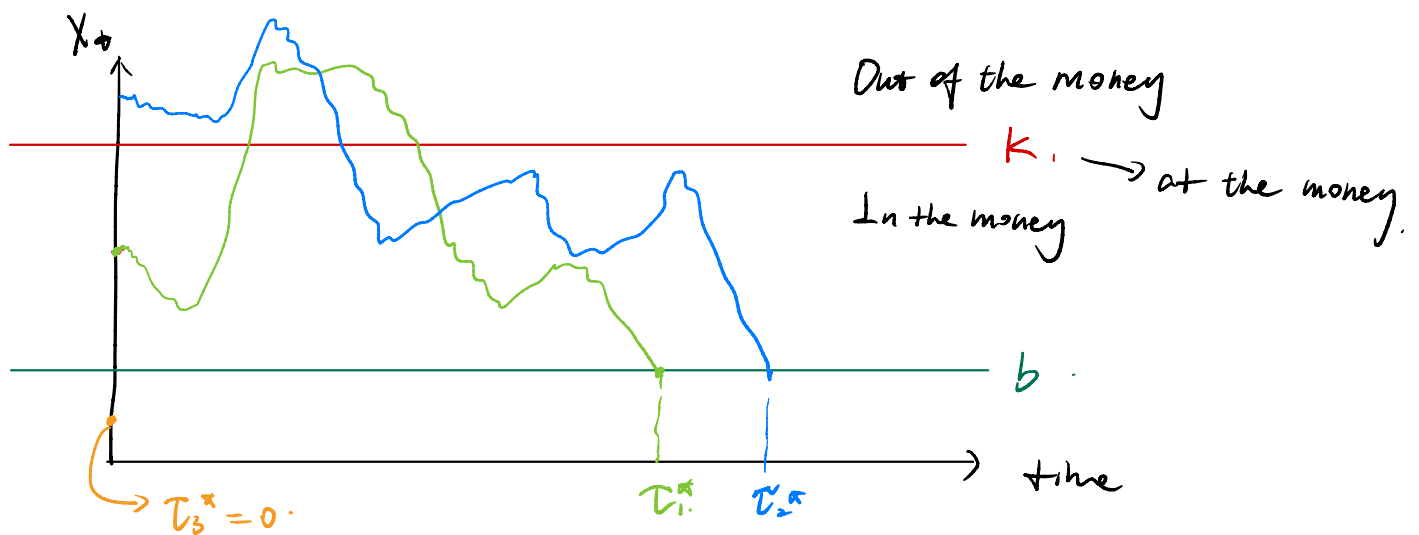
when $x < k$, $g(x) > 0$, but can't wait forever, because of the penalisation in time.

There must be a threshold $b \in (0, k)$, s.t.

$$C = (b, \infty), \quad D = (0, b]$$

• What's the optimal strategy τ^* ?

$$\tau^* = \inf \{ t \geq 0 : X_t \in D \}$$



Step 2: Write down the free-boundary problem.

Assume candidate \hat{V} solves:

$$(*) \quad \begin{cases} (\gamma - \delta) \hat{V}_x + \frac{1}{2} \sigma^2 x^2 \hat{V}_{xx} - r \hat{V} = 0, & x > b \\ \hat{V}(x) = k - x, & x \leq b. \\ \hat{V}_x(b) = -1. \end{cases}$$

$\hookrightarrow x \leq b < k$.

\downarrow
"Smooth fit"

Step 3 . Make an ansatz and solve (*).

Ansatz: $\hat{V}(x) = x^\delta$. Plug in (*):

$$(r-\delta) \cancel{\delta} x^\delta + \frac{1}{2} \sigma^2 \delta(\delta-1) \cancel{x^\delta} - r \cancel{x^\delta} = 0, \quad x > b$$

$$\Rightarrow \frac{1}{2} \sigma^2 \delta^2 + (r-\delta-\frac{1}{2} \sigma^2) \delta - r = 0.$$

quadratic eqn, roots with opposite signs!

$$\delta_{\pm} = \frac{1}{\sigma^2} \left(-(r-\delta-\frac{1}{2} \sigma^2) \pm \sqrt{(r-\delta-\frac{1}{2} \sigma^2)^2 + 2\sigma^2 r} \right).$$

when $\delta_- < 0$. (obvious).

$$\delta_+ \geq 1. \quad (\text{polynomial}(1) = -\delta \leq 0).$$

$$\hookrightarrow \delta_+ = 1 \text{ when } \delta = 0$$

The general solution for \hat{V} is

$$\hat{V}(x) = C_1 x^{\delta_+} + C_2 x^{\delta_-}.$$

$$\text{As } x \rightarrow \infty, \hat{V}(x) \rightarrow 0. \quad \Rightarrow C_1 = 0$$

(Why? when current stock price is high, it's very unlikely to drop below k).

$$\Rightarrow \hat{V}(x) = C_2 x^{\delta_-}.$$

"Continuous fit" bdr condition.

$$C_2 b^{\delta_-} = \hat{V}(b) = g(b) = k - b.$$

$$\Rightarrow C_2 = \frac{k-b}{b^{\delta-1}}$$

- "Smooth fit" bdr condition

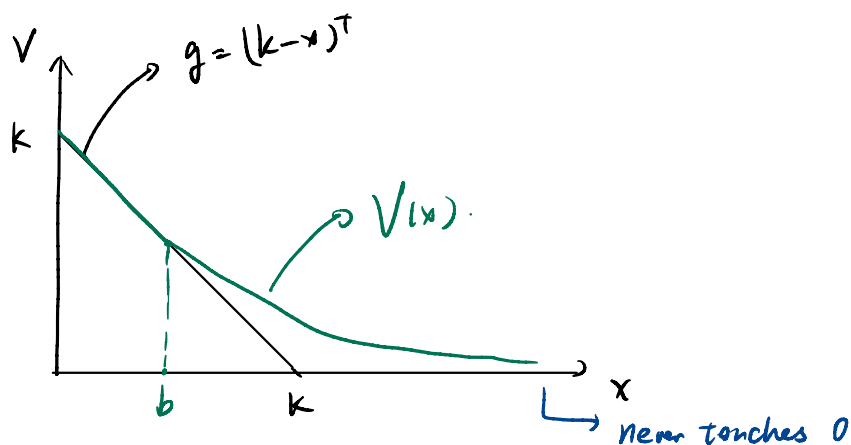
$$(C_2 \delta - 1) b^{\delta-1} = \hat{V}'_x(b) = g'_x(b) = -1.$$

$$\Rightarrow b = \frac{k \delta}{\delta - 1} \quad (\text{Sanity check: } 0 < b < k).$$

$$\hat{V}(x) = \begin{cases} k - x, & x \in (0, b] \\ \frac{k-b}{b^{\delta-1}} x^{\delta-1}, & x > b \end{cases}$$

Finally, by the verification thm, $\hat{V} \equiv V$, and τ^* is an optimal strategy.

(How does it look like?).



What about calls?

Example 12.2 (Perpetual American Call).

Similarly, we consider

$$dX = (r - \delta) X dt + \sigma dB_t, \quad X_0 = x.$$

with payoff $g(x) = (x - k)^+$.

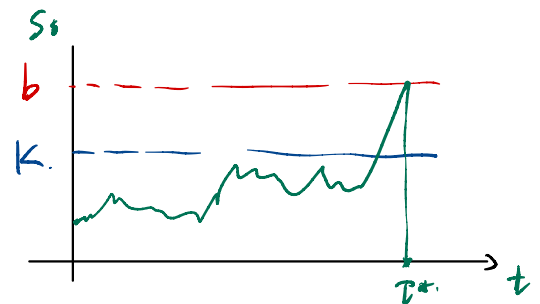
Step 1.
$$V(x) = \sup_{\tau} \mathbb{E}_x \left[e^{-r\tau} (X_\tau - k)^+ \right].$$

There must be a barrier $b > k$ s.t. when X_t is big enough, we exercise. Otherwise we wait.

$$C := (0, b)$$

$$D := [b, \infty)$$

$$\tau^* := \inf \{ t : X_t \in D \}$$



Step 2. Let \hat{V} solve:

$$\begin{cases} (r - \delta) x \hat{V}_x + \frac{1}{2} \sigma^2 x^2 \hat{V}_{xx} - r \hat{V} = 0, & x < b. \\ \hat{V}(x) = x - k, & x \geq b. \\ \hat{V}_x(b) = 1 \end{cases}$$

Step 3. Similarly, we obtain a general solution for \hat{V} :

$$\hat{V}(x) = C_1 x^{\delta_+} + C_2 x^{\delta_-} \rightarrow < 0.$$

as $x \rightarrow 0$, $\hat{V} \rightarrow 0$. \Rightarrow only consider δ_+ .

plug in "continuous fit" and "smooth fit":

$$C_1 = \frac{b - k}{b^{\delta_+}}.$$

$$b = \frac{k \delta_+}{\delta_+ - 1} \leftarrow \text{ok if } \delta_+ > 1. \\ \text{ie. } \delta > 0.$$

when $\delta_+ > 1$.

$$V = \hat{V}(x) = \begin{cases} \frac{b-k}{b^{\delta_+}} \cdot x^{\delta_+}; & x \in (0, b) \\ x - k, & x \geq b \end{cases}$$

when $\delta_+ = 1$: $b = \infty$. it's never optimal to exercise!

Remark. when $T < \infty$, it's still never optimal to exercise an American call early!

prf. Let $\tau \leq T$ be any stopping time. suppose we exercise at τ . we get $(X_\tau - k)^+$, the value at 0 would be

$$\mathbb{E} [e^{-r\tau} (X_\tau - k)^+] \leq \mathbb{E} [(e^{-r\tau} X_\tau - k e^{-rT})_+] \\ \uparrow \\ \tau \leq T.$$

Recall. $M_t := e^{-rt} X_t$ is a \mathbb{Q} -m.g. for any convex fcn φ :

$$\mathbb{E} [\varphi(M_T)] = \mathbb{E} [\mathbb{E} [\varphi(M_T) | \mathcal{F}_\tau]]$$

$$\geq \mathbb{E} [\varphi(\mathbb{E} [M_T | \mathcal{F}_\tau])]$$

Jensen's \nearrow

$$= \mathbb{E} [\varphi(M_\tau)] \\ \text{m.g. } \nearrow$$

Therefore, since $(X-C)_+$ convex.

$$\begin{aligned}\mathbb{E}[(e^{-rt}X_t - ke^{-rT})_+] &\leq \mathbb{E}[(e^{-rT}X_T - ke^{-rT})_+] \\ &= \mathbb{E}[e^{-rT}(X_T - k)_+].\end{aligned}$$

\Rightarrow Should always wait until T !

Therefore, price of an American call = European call.
(No dividend, $\delta = 0$).

Remark what happens if $T < \infty$?

(put on call when $\delta > 0$).

- Clearly, V is time-dependent. $V = V(t, x)$.
- The exercise threshold becomes time-dependent: $b = b(t)$.
- $b(T) = K$. (why? at T we have to make an immediate choice).

The free-boundary now becomes. (e.g. put)

$$\left\{ \begin{array}{ll} V_t + \mathcal{L}V - rV = 0. & \text{in } C. \\ V(t, x) > (k-x)^+ & \text{in } C \\ V(t, x) = (k-x)^+ & \text{in } D \\ V_x(t, x) = -1. & x = b(t). \end{array} \right.$$

- Explicit solution is no longer possible. Can study the

Structural properties . .