

Lecture 4. PDEs and SDEs: the connection.

- Recall the solution of $dX_t = \mu(X_t)dt + \sigma(X_t)dB_t$ is called an "Ito diffusion", \Rightarrow diffusion of a dust particle in water.
 - Similarly, in the world of PDEs, "diffusion eqns" model the same thing.
- For now let's consider the aforementioned Ito diffusions.

Def 4.1. (Infinitesimal generators).

Let X_t be a (time-hom) Ito diffusion. $\in \mathbb{R}^n$, for suitable $f: \mathbb{R}^n \rightarrow \mathbb{R}$,

The infinitesimal generator \mathcal{L} of X_t is defined as.

$$(\mathcal{L}f)(x) = \lim_{t \downarrow 0} \frac{1}{t} \left(\mathbb{E}_x [f(X_t)] - f(x) \right)$$

when the limit exists.

Remark i). notation: " \mathbb{E}_x " = $\mathbb{E}[\cdot | X_0 = x]$, " $\mathbb{E}_{t,x}$ " = $\mathbb{E}[\cdot | X_t = x]$

ii). Why time-homogeneity?

In the inhomogeneous case, we can make it homogeneous by setting

$$dX = 1 dt + 0 dB.$$

iii). What are suitable f 's? e.g., $f \in C_0^2(\mathbb{R}^n)$

iv). Set $f(x) = \mathbb{1}_{\{x \in D\}}$. we get infinitesimal

\hookrightarrow twice differentiable,
compact support.

change of the prob. distribution.

Thm 4.2 Let X_t be 1-dim Ito diffusion, $dX_t = \mu(X_t) dt + \sigma(X_t) dB_t$

Let $f \in C^2(\mathbb{R}^n)$. then $\mathcal{L}f(x)$ exists for all $x \in \mathbb{R}^n$, and

$$(\mathcal{L}f)(x) = \mu(x) \frac{\partial f}{\partial x} + \frac{1}{2} \sigma^2(x) \frac{\partial^2 f}{\partial x^2}$$

If $X_t \in \mathbb{R}^n$, then

$$(\mathcal{L}f)(x) = \sum_i \mu_i(x) \frac{\partial f}{\partial x_i} + \frac{1}{2} \sum_{i,j} (\sigma \sigma^T)_{ij} \frac{\partial^2 f}{\partial x_i \partial x_j}$$

Prf: (also as an example)

It suffices to show that for a 1-d BM,

$$\mathcal{L} = \frac{1}{2} \frac{d^2}{dx^2}$$

(i.e. the generator of BM is $\frac{1}{2} \Delta$) ↪ Laplacian op.

Apply Ito's formula to $f(B_{t+s})$ with $B_t = x$:

$$\begin{aligned} \mathcal{L}f(x) &= \lim_{s \downarrow 0} \frac{1}{s} \left[\mathbb{E}_x [f(B_{t+s})] - f(x) \right] \\ &= \lim_{s \downarrow 0} \frac{1}{s} \left[\mathbb{E}_x \left[\cancel{f(x)} + \int_t^{t+s} \underbrace{f'(B_u)}_0 dB_u + \int_t^{t+s} \frac{1}{2} f''(B_u) du \right] - \cancel{f(x)} \right] \\ &= \frac{1}{2} \frac{d}{ds} \left(\int_t^{t+s} \mathbb{E}[f''(B_u)] du \right) \\ &= \frac{1}{2} f''(B_t) = \frac{1}{2} f''(x). \quad \square \end{aligned}$$

Notation: $f = f(t, x) \in C^{1,2}$, still define $(\mathcal{L}f)(t, x) = \mu f_x + \frac{1}{2} \sigma^2 f_{xx}$

\mathcal{L} only applies to x .

E.X. 4.3 (GBM)

X_t solves $dX = rX dt + \sigma X dB$.

$$(\mathcal{L}f)(x) = rx f_x + \frac{1}{2} \sigma^2 x^2 f_{xx}$$

What does this generator do?

Describes the movement of the process in a very small time interval.

- Itô's formula can be written as

$$\begin{aligned} df(t, X_t) &= \frac{\partial f}{\partial t} dt + \mu \frac{\partial f}{\partial x} dt + \frac{1}{2} \sigma^2 \frac{\partial^2 f}{\partial x^2} dt + \sigma \frac{\partial f}{\partial x} dB_t \\ &= \underbrace{\left(\frac{\partial f}{\partial t} + (\mathcal{L}f)(t, X_t) \right)}_{\text{maps to the "drift coefficient"}} dt + \sigma \frac{\partial f}{\partial x} dB_t \end{aligned}$$

maps to the "drift coefficient".

$$df = \left(f_t + \mathcal{L}f \right) dt + \text{something} \cdot dB_t$$

Stochastic representation for PDE.

- Consider the following PDE of $u(t, x)$

$$\begin{cases} u_t + \mathcal{L}u = 0 \\ u(T, x) = \Phi(x) \end{cases}$$

where $(\mathcal{L}u)(t, x) = \mu u_x + \frac{1}{2} \sigma^2 u_{xx}$.

(Assume this PDE has a $C^{1,2}$ solution).

Apply Itô's formula to $u(t, X_t)$, in the interval from t to T :

$$u(T, X_T) = u(t, X_t) + \int_t^T (u_t + \mathbb{L}u) ds + \int_t^T \sigma u_x dB_s$$

obs: $\Phi(X_T)$

$= 0$, by PDE

things will be nicer if this is 0.

Take expectation! Given $X_t = x$, we have.

$$\mathbb{E}_{t,x} [\Phi(X_T)] = \underbrace{\mathbb{E}_{t,x} [u(t, X_t)]}_{u(t,x)} + \underbrace{\mathbb{E}_{t,x} \left[\int_t^T \sigma u_x dB_s \right]}_0$$

\Rightarrow The solution

$$u(t,x) = \mathbb{E}_{t,x} [\Phi(X_T)]$$

Solution to a PDE.

Expectation of a r.v.

Thm 4.4. (Feynman-Kac formula).

Consider S.P. X_t which solves.

$$dX_s = \mu(s, X_s) ds + \sigma(s, X_s) dB_s, \text{ with } X_t = x.$$

\rightarrow time horizon / expiry time

Let $D \subset \mathbb{R}^n$ be a connected open domain, $T > 0$. Consider

deterministic functions:

$$\Gamma: \mathbb{R}_+ \times \mathbb{R}^n \rightarrow \mathbb{R}_+ \quad (\text{discount rate function})$$

$$\Psi: \mathbb{R}_+ \times \mathbb{R}^n \rightarrow \mathbb{R} \quad (\text{running payoff function})$$

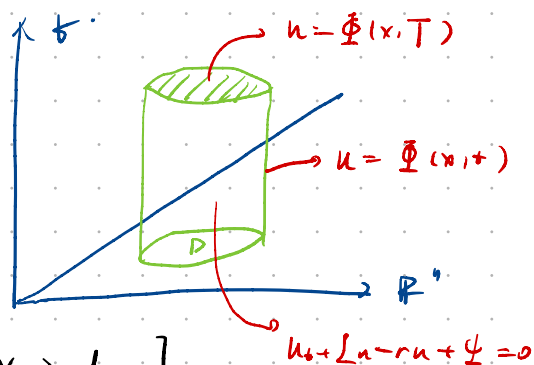
$$\Phi: \mathbb{R}^n \rightarrow \mathbb{R} \quad (\text{final payoff function})$$

then the unique solution to the PDE:

$$\begin{cases} u_t + Lu - ru + \Psi = 0 & \text{in } [0, T) \times D. \quad \rightarrow \text{cylinder set} \\ u = \Phi & \text{in } ([0, T) \times \partial D) \cup (\{T\} \times D). \end{cases}$$

Terminal condition

boundary condition



where $u \in C^{1,2}$ is given by

$$u(t, x) = \mathbb{E}_{+, x} \left[d(t, T) \Phi(X_T) + \int_t^T d(t, s) \Psi(s, X_s) ds \right]$$

$$\text{where } d(t_1, t_2) = \exp\left(-\int_{t_1}^{t_2} r(s, X_s) ds\right)$$

Remark: i) It's easy to derive when $D = \mathbb{R}^n$, $r \geq 0$ constant,

Idea: consider $Y_s = e^{-r(s-t)} u(s, X_s)$ (Exercise).

ii) In finance, Φ : final payoff, Ψ : dividend.

Application: Terminal / Initial value problems.

E.X. 4.5 Solve the PDE

$$\begin{cases} u_t + \frac{1}{2} u_{xx} = 0 \\ u(x, T) = x^2 \end{cases}$$

By FK, $u(x, t) = \mathbb{E}_{+, x} [X_T^2]$, where $dX_t = dB_t$.

$$= \mathbb{E}[B_T^2 | B_t = x]$$

$$= \mathbb{E}[(x + B_{T-t})^2]$$

$$= x^2 + \mathbb{E}[B_{T-t}^2] + 2x \mathbb{E}[B_{T-t}]$$

$$= x^2 + T - t.$$

→ Check it in the PDE!

Can we make it stronger?

- Take it to stopping times, restrict it to Itô diffusions.

Thm 4.6 (Dynkin's formula)

Let X_t be an Itô diffusion, and $f \in C_0^2(\mathbb{R}^n)$. Let τ be a \mathcal{F}_0^- stopping time such that $\mathbb{E}[\tau] < \infty$. Then.

$$\mathbb{E}_x[f(X_\tau)] = f(x) + \mathbb{E}_x\left[\int_0^\tau \Delta f(X_s) ds\right].$$

(i.e. The properties we know hold also for stopping times!).

Idea of proof

→ very commonly used!

i). recall that $\tau \wedge n$ is a stopping time.

ii). (Doob's Optional Sampling thm). "OST".

If X_t is an integrable mg, and τ is a bounded \mathcal{F}_0^- -stopping time,

then $\mathbb{E}[X_{\tau \wedge n}] = \mathbb{E}[X_0]$.

See the next page for the proof of Dynkin's

Remark. Further reading: "Wald's identities for BM".

[This page is not presented during the lecture].

(proof of Dynkin's formula)

Want : $\mathbb{E}_x \left[\sum_{i,k} \int_0^\tau \sigma_{ik} \frac{\partial f}{\partial x_i} dB_k \right] = 0.$
 \hookrightarrow b.d.d.

Note that for g b.d.d. $|g| \leq M$. then for all integers

$$\mathbb{E}_x \left[\int_0^{\tau \wedge k} g(Y_s) dB_s \right] = \mathbb{E}_x \left[\int_0^k \underbrace{g(Y_s)}_{\substack{\hookrightarrow g \\ \text{F}_s\text{-mble.}}} \cdot \underbrace{\mathbb{1}_{s \leq \tau}}_{\substack{\hookrightarrow \text{F}_s\text{-mble.}}} dB_s \right] = 0.$$

$$\mathbb{E}_x \left[\left(\int_0^\tau g(Y_s) dB_s - \int_0^{\tau \wedge k} g(Y_s) dB_s \right)^2 \right] = \mathbb{E}_x \left[\int_{\tau \wedge k}^\tau g^2(Y_s) ds \right].$$

\uparrow
Itô isometry.

$$\leq M^2 \cdot \mathbb{E}_x [\tau - \tau \wedge k].$$

Take limits on both sides.

$$\int_0^{\tau \wedge k} g(Y_s) dB_s \xrightarrow{L^2} \int_0^\tau g(Y_s) dB_s.$$

$$\Rightarrow \int_0^{\tau \wedge k} g(Y_s) dB_s \xrightarrow{\text{a.s.}} \int_0^\tau g(Y_s) dB_s.$$

$$\Rightarrow \mathbb{E}_x \left[\int_0^\tau g(Y_s) dB_s \right] = 0.$$

E.X. 4.7 (How long does it take to hit?) \rightarrow size of domain, distance from the bdr.

Let $B_t \in \mathbb{R}$ be a BM. w. $B_0 = 0$. Let τ be the first time B_t exits from the interval $(-a, a)$?

i) Is $E[\tau]$ finite? For now let's accept it is. (To prove: F5.)

ii) What is $E[\tau]$?

By Dynkin's formula, let $f(x) = x^2$

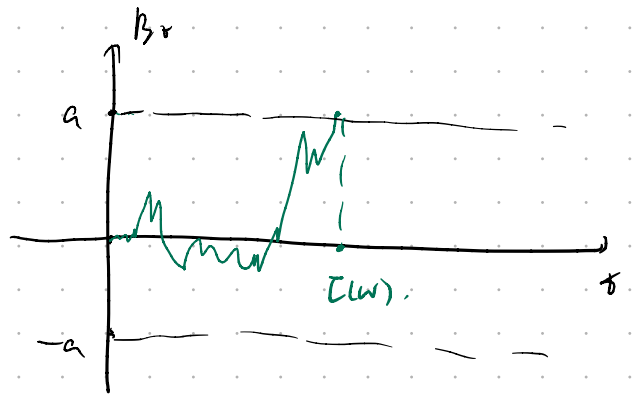
$$E[f(B_\tau)] = f(B_0) + E\left[\int_0^\tau \frac{1}{2} f''(B_s) ds\right]$$

$$E[(B_\tau)^2] = 0 + E\left[\int_0^\tau ds\right] = E[\tau]$$

$$\Rightarrow E[\tau] = 1 \cdot a^2 = a^2.$$

This makes sense! $B_t \sim \sqrt{t}$,

(higher dimensions: F5).



Exercise 1. Let $\tau = \inf\{t > 0 : B_t \notin (-a, b)\}$. Determine $E[\tau]$.

E.X. 4.8 (An interesting example: when Dynkin fails).

Case 1 . $E[\tau] = \infty$.

• Let $\tau_a := \inf\{t > 0 : B_t = a\}$, $a > 0$, then $E[\tau_a] = \infty$.

Prf. (First step analysis).

$$\text{Let } T_1 = \inf \{ t > 0 : B_t \in \{-a, a\} \}.$$

$$T_2 = \inf \{ t > 0 : B_t = 0 \text{ with } B_0 = -a \}.$$

$$\text{Then } \mathbb{E}[T_a] = \mathbb{E}[T_1] + \frac{1}{2} \cdot 0 + \frac{1}{2} (\mathbb{E}[T_2] + \mathbb{E}[T_a])$$

$(0 \rightarrow \pm a)$ $(-a \rightarrow 0)$ $(0 \rightarrow a)$

$$\mathbb{E}[T_a] = \mathbb{E}[T_1] + \mathbb{E}[T_a]$$

\nearrow
 $\mathbb{E}[T_a] = \mathbb{E}[T_2]$

Only solution: $\mathbb{E}[T_a] = \infty$, since $\mathbb{E}[T_1], \mathbb{E}[T_a] > 0$.

What if we apply Dynkin?

Let $f(x) = x$. by Dynkin

$$\mathbb{E}[B_\tau] \stackrel{?}{=} B_0 + \mathbb{E} \left[\int_0^\tau 0 dt \right] = B_0 = 0.$$

But $\mathbb{E}[B_\tau] = a$! Dynkin's fails.

Conclusion: $\mathbb{E}[\tau] < \infty$ is an important assumption!

Remark. In this example, $\mathbb{E}[\tau] = \infty$. However $P(\tau < \infty) = 1$

Case 2. τ is not a stopping time. ↗ "running maximum"

$$\text{e.g. } \tau = \inf \{ t \geq 1 : B_t = \max_{t \leq 1} B_t \}.$$

$$\mathbb{E}[B_\tau] = \mathbb{E} \left[\max_{t \leq 1} B_t \right] > 0. \quad \text{fails!}$$

Conclusion: τ is a stopping time is also an important assumption!

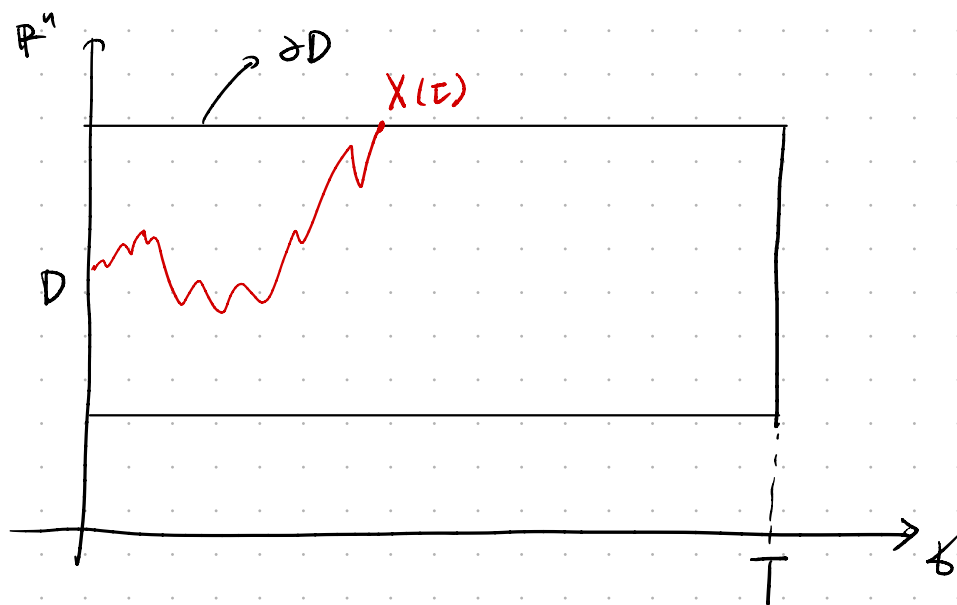
• Now take $D \subset \mathbb{R}^n$, $\tau_D := \inf\{t > 0 : X \notin D\}$.

such that $\mathbb{E}_x[\tau_D] < \infty$ for all $x \in D$,

Thm 4.9. Let $\tau_D := \inf\{t : X_t \notin D\}$ and $\tau = \tau_D \wedge T$. Then the

Feynman-Kac can be taken up to τ instead of T .

$$u(t, x) = \mathbb{E}_{t, x} \left[d(t, \tau) \Phi(X_\tau) + \int_t^\tau d(t, s) \Psi(s, X_s) ds \right]$$



Next lecture: we take $T \rightarrow \infty$.